JOURNAL OF RESEARCH of the National Bureau of Standards – B. Mathematics and Mathematical Physics Vol. 71B, No. 1, January–March 1967

## **On Involutions**

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(December 7, 1966)

Two methods are described of constructing real functions over the reals which are one-to-one, assume every real value and are their own inverses, and several examples are given. It is also shown that such a function, if everywhere continuous, is either the function  $f(x) \equiv x$  or else is strictly decreasing.

Key Words: Inverses, involutions, real functions.

1. We shall consider real functions f whose domain is the set of real numbers, which take on every real value, are one-to-one, and satisfy for every real x,  $f^{-1}(x) = f(x)$ , where  $f^{-1}$  is the inverse function of f. We denote by I the set of all such functions. Recall that functions which are their own inverses are called *involutions*.

Suppose that a real function f has as its domain the set of real numbers. Then it belongs to I if and only if

$$f(f(x) = x \text{ for every real } x.$$
(1)

Indeed, if  $f \in I$ , then for every real x,  $f(f(x)) = f(f^{-1}(x)) = x$ . Conversely, if (1) holds, then f takes on every real value, is one-to-one (for  $f(x_1) = f(x_2)$  implies  $x_1 = f(f(x_1)) = f(f(x_2)) = x_2$ ), and for every real x,  $f^{-1}(x) = f(x)$ .

Note that the graph of every f in I is symmetric in the line y=x.

Conversely, if G is a set in the x, y plane, symmetric in the line y=x and containing, for every real x, a unique point whose abscissa is x, then G is the graph of a function belonging to I.

2. One way of obtaining functions in I is the following. Start with a real function g(x, y) whose domain is the set of all ordered pairs of real numbers, and which is such that g(x, y) = 0 implies g(y, x) = 0. (This property holds, e.g., if g is symmetric, i.e., if for every real x, y, we have g(y, x) = g(x, y).) Suppose that for every real x, there is a unique real y (to be denoted f(x)) such that g(x, y) = 0. Then f (with domain the set of reals) belongs to I. Indeed, for every real x,

$$g(f(x), x) = g(x, f(x)) = 0.$$

and consequently f(f(x)) = x.

EXAMPLE 1. Let  $g(x, y) \equiv x + y - c$ , c being an arbitrary real constant. We obtain from it the function  $f(x) \equiv c - x$  belonging to *I*.

EXAMPLE 2. Let  $g(x, y) \equiv x - y$ . The corresponding  $f \epsilon I$  is  $f(x) \equiv x$ .

EXAMPLE 3. Let  $g(x, y) \equiv x^3 + y^3 - c$ , *c* being an arbitrary real constant. We get from it the function  $f(x) \equiv \sqrt[3]{c-x^3} \epsilon I$ .

3. Another method of obtaining functions in I is based on the last paragraph of section 1. We illustrate this method by the following

EXAMPLE 4. In the X, Y plane consider the hyperbola  $X^2 - \frac{1}{2}Y^2 = 1$ . Let R, L denote, respectively, its righthand and left-hand branches. Consider now a new coordinate system, x, y, obtained from the X, Y system by a clockwise rotation of 45°. In the new coordinate system the equation of R (which is symmetric in the line y = x) is

$$y = -3x + 2(2x^2 + 1)^{1/2}$$
.

Thus,  $f(x) \equiv -3x + 2(2x^2 + 1)^{1/2}$  belongs to *I*. Similarly, the equation of *L* in the new coordinate system is

$$y = -3x - 2(2x^2 + 1)^{1/2}$$

and consequently,  $f(x) \equiv -3x - 2(2x^2 + 1)^{1/2}$  belongs to *I*.

4. Consider the functions in *I* which are everywhere continuous. Since such a function takes on every real value exactly once, it must be, throughout the real line, either strictly increasing or strictly decreasing. For example,  $f(x) \equiv x$  is a function in *I* which is strictly increasing. It is interesting to note that all other everywhere continuous functions in *I* are strictly decreasing. Indeed, let  $F(x)(\not\equiv x)$  be an everywhere continuous function in *I*, be an everywhere continuous function in *I*. Then its graph contains two points which do not lie on the line  $y \equiv x$ , but which are symmetric in this line. Let  $(x_1, y_1), (x_2, y_2)$  (with  $x_1 < x_2$ ) be such points. Then  $y_1 > y_2$  (draw a figure!). So  $F(x_1) > F(x_2)$ , and consequently, *F* is strictly decreasing.

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5. Let us examine the smoothness of the various examples we have of functions belonging to *I*. The functions c-x and x of Examples 1 and 2 are differentiable throughout the real line; in fact they are analytic at each real point. The function  $f(x) \equiv \sqrt[3]{c-x^3}$  of Example 3 is everywhere continuous. If c=0, it reduces to -x. Otherwise, it is everywhere differentiable except at the point  $x = \sqrt[3]{c}$ , where it is not.

Let us now look at the functions f of Example 4. The function  $2z^2 + 1$  of the complex variable z vanishes at  $2^{-1/2}i$ ,  $-2^{-1/2}i$  and nowhere else. Consequently, the real functions  $-3x + 2(2x^2 + 1)^{1/2}$ ,  $-3x - 2(2x^2 + 1)^{1/2}$ of Example 4, are analytic at every point of the x axis.

## (Paper 71B1-192)